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ALMOST GEODESIC MAPPINGS OF THE SECOND TYPE OF SPACES WITH AFFINE CONNECTION ONTO TWO-SYMMETRIC SPACES

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Abstract. In the paper we consider canonical almost geodesic mappings of type $\pi_2(e)$ of spaces with affine connection onto two-symmetric spaces. The main equations for the mappings are obtained as a closed mixed system of PDEs of Cauchy type. We have found the maximum number of essential parameters which the solution of the system depends on.

Keywords: Almost geodesic mapping, spaces with affine connection, two-symmetric spaces

Mathematics subject classification: Primary 53B05; Secondary 53B99

1 Introduction

The paper is devoted to further study of the theory of almost geodesic mappings of affinely connected spaces. The theory goes back to the paper [16] of Levi-Civita, in which the problem on the search for Riemannian spaces with common geodesics was stated and solved in a special coordinate system. We note a remarkable fact that this problem is related to the study of equations of dynamics of mechanical systems.

The theory of geodesic mappings has been developed by T. Thomas, H. Weyl, P. A. Shirokov, A. S. Solodovnikov, N. S. Sinyukov, A. V. Aminova, J. Mikeš, and others, see [19, 23, 27].

Issues arisen by the exploration were studied by V. F. Kagan, G. Vrançeanu, Ya. L. Shapiro, D. V. Vedenyapin et al. The authors discover special classes of (n - 2)-projective spaces.

In [24], Petrov introduced the notion of quasi-geodesic mappings. In particular, holomorphically projective mappings of Kählerian spaces are special quasi-geodesic mappings; they were examined by T. Otsuki and Y. Tashiro, M. Prvanović and others.

A natural generalization of these classes of mappings is the class of almost geodesic mappings introduced by Sinyukov (see [26, 27, 28]); he also specified three types of almost geodesic mappings π_1 , π_2 , π_3 .

The types of almost geodesic mappings π_1 , π_2 , π_3 can intersect. The problem of completeness of classification had long remained u nresolved. Berezovskii and Mikeš [4, 5] proved that for n > 5 other types of almost geodesic mappings except π_1 , π_2 , and π_3 do not exist.

The theory of almost geodesic mappings was developed by V. S. Sobchuk [30, 29], N. V. Yablonskaya [33], V. E. Berezovskii, J. Mikeš [1, 2, 3, 5, 6, 7, 8, 9, 10, 12, 11, 23, 21], Lj. S. Velimirović, N. Vesić, M. S. Stanković [32] et al. An interesting generalization is rotary mapping, see [22].

The paper is devoted to study canonical almost geodesic mappings of type $\pi_2(e)$ $(e = \pm 1)$ of spaces with affine connections onto two-symmetric s paces. The main equations for the mappings are obtained as a closed mixed system of PDEs of Cauchy type. We have found the maximum number of essential parameters which the general solution of the system depends on.

The investigations use local coordinates. We assume that all functions under consideration are sufficiently differentiable, n is the dimension of the studied spaces, and we suppose that n > 2.

2 Basic definitions of almost geodesic mappings of spaces with affine connections

Let us recall the basic definition, formulas and theorems of the theory presented in [9, 23, 21, 26, 27, 28].

Consider a space A_n with affine connection Γ_{ij}^h without torsion. The space is referred to coordinates x^1, x^2, \ldots, x^n .

A curve $l: x^h = x^h(t)$ in the space A_n is a *geodesic* when its tangent vector $\lambda^h(t) = dx^h(t)/dt$ satisfies the equations

$$\lambda_1^h = \rho(t) \cdot \lambda^h,$$

where

$$\lambda_1^h \equiv \lambda_{,\alpha}^h \lambda^\alpha = \frac{d\lambda^h(t)}{dt} + \Gamma^h_{\alpha\beta}(x(t))\lambda^\alpha(t)\lambda^\beta(t)$$

and $\rho(t)$ is some function of t. We denote by comma "," the covariant derivative with respect to the connection of the space A_n .

A curve in the space A_n is an *almost geodesic* when its tangent vector $\lambda^h(t) = dx^h(t)/dt$ satisfies the equations

$$\lambda_2^h = a(t) \cdot \lambda^h + b(t) \cdot \lambda_1^h$$

where $\lambda_2^h \equiv \lambda_{1,\alpha}^h \lambda^{\alpha}$, and a(t), b(t) are some functions of the parameter t.

We say that a diffeomorphism $f: A_n \to \overline{A}_n$ is an *almost geodesic mapping* if any geodesic curve of A_n is mapped under f onto an almost geodesic curve in \overline{A}_n .

Suppose, that a space A_n with affine connection $\Gamma_{ij}^h(x)$ admits a mapping f onto space \overline{A}_n with affine connection $\overline{\Gamma}_{ij}^h(x)$, and the spaces are referred to the common coordinate system x^1, x^2, \ldots, x^n .

The tensor

$$P_{ij}^{h}(x) = \overline{\Gamma}_{ij}^{h}(x) - \Gamma_{ij}^{h}(x), \qquad (1)$$

is called a *deformation tensor* of the connections $\Gamma_{ij}^h(x)$ and $\overline{\Gamma}_{ij}^h(x)$ with respect to the mapping f. The symbols $\Gamma_{ij}^h(x)$ and $\overline{\Gamma}_{ij}^h(x)$ are components of affine connections of the spaces A_n and \overline{A}_n respectively.

According to [27, 28], a necessary and sufficient condition for the mapping f of a space A_n onto a space \overline{A}_n to be almost geodesic is that the deformation tensor $P_{ij}^h(x)$ of the mapping f in the common coordinate system x^1, x^2, \ldots, x^n has to satisfy the condition

$$A^{h}_{\alpha\beta\gamma}\lambda^{\alpha}\lambda^{\beta}\lambda^{\gamma} = a \cdot P^{h}_{\alpha\beta}\lambda^{\alpha}\lambda^{\beta} + b \cdot \lambda^{h},$$

where λ^h is an arbitrary vector, a and b are certain functions of variables x^1, x^2, \ldots, x^n and $\lambda^1, \lambda^2, \ldots, \lambda^n$. The tensor A^h_{ijk} is defined as

$$A_{ijk}^{h} \stackrel{\text{def}}{=} P_{ij,k}^{h} + P_{ij}^{\alpha} P_{\alpha k}^{h}.$$

A mapping $f: A_n \to \overline{A}_n$ is called an *almost geodesic of type* π_2 , if the conditions

$$P_{ij}^{h} = \delta_{(i}^{h}\psi_{j)} + F_{(i}^{h}\varphi_{j)}, \qquad (2)$$

$$F_{(i,j)}^{h} + F_{\alpha}^{h} F_{(i}^{\alpha} \varphi_{j)} = \delta_{(i}^{h} \mu_{j)} + F_{(i}^{h} \rho_{j)},$$
(3)

holds. Here ψ_i , φ_i , μ_i , ρ_i are some covectors, F_i^h is a tensor of type (1, 1), δ_i^h is the Kronecker delta and round bracket is denoted symmetrization.

We consider mappings $\pi_2: A_n \to \overline{A}_n$ characterized locally in a common coordinate system by the equations (2) and (3) as corresponding to $F_i^h(x)$.

A mapping π_2 satisfies a *mutuality condition* if the inverse mapping is also an almost geodesic of type π_2 and corresponding to the same affinor $F_i^h(x)$.

The mappings π_2 satisfying a *mutuality condition* will be denoted as $\pi_2(e)$, where $e = \pm 1, 0$, and for F the following identity holds:

$$F^2 = -eI. (4)$$

As it was proved in [31], in the case when $e = \pm 1$ the basic equations of the mappings $\pi_2(e)$ can be written as the equations (2), (3) and (4):

$$F_{i,j}^{h} = F_{ij}^{h}, \qquad F_{ij,k}^{h} = \stackrel{6}{\Theta}_{ijk}^{h}, \qquad \mu_{i,j} = \mu_{ij}, \qquad \mu_{ij,k} = \stackrel{7}{\Theta}_{ijk},$$
 (5)

$$F^{h}_{(ij)} = F^{h}_{(i}\mu_{j)} - \delta^{h}_{(i}F^{\alpha}_{j)}\mu_{\alpha}, \qquad \mu_{(ij)} = \stackrel{5}{\Theta}_{ij},$$

$$\tag{6}$$

where $F_i^h(x)$, $F_{ij}^h(x)$, $\mu_i(x)$, $\mu_{ij}(x)$ are unknown functions. The above tensors are as follows:

$$\begin{split} & \stackrel{1}{\Theta}_{ijk}^{h} \equiv \stackrel{2}{\Theta}_{ijk}^{h} + \stackrel{2}{\Theta}_{kji}^{h} - \stackrel{2}{\Theta}_{jki}^{h} + 2F_{\alpha}^{h}R_{kji}^{\alpha} - F_{i}^{\alpha}R_{\alpha jk}^{h} + F_{j}^{\alpha}R_{\alpha ik}^{h} + F_{k}^{\alpha}R_{\alpha ij}^{h}, \\ & \stackrel{2}{\Theta}_{ijk}^{h} \equiv \mu_{(i}F_{j)k}^{h} - \delta_{(i}^{h}F_{j)k}^{\alpha}\mu_{\alpha}, \\ & \stackrel{3}{\Theta}_{ijk}^{h} \equiv \stackrel{2}{\Theta}_{ijk}^{h} - \stackrel{2}{\Theta}_{kji}^{h} + F_{j}^{\alpha}R_{\alpha ik}^{h} - F_{\alpha}^{h}R_{jik}^{\alpha}, \\ & \stackrel{4}{\Theta}_{jk} \equiv F_{\beta}^{\alpha}\stackrel{1}{\Theta}_{\alpha jk}^{\beta} + 2F_{\beta j}^{\alpha}F_{\alpha k}^{\beta}, \\ & \stackrel{5}{\Theta}_{jk} \equiv \frac{1}{(n-1-F_{\alpha}^{\alpha})^{2}-1} \left(\left(n-1-F_{\alpha}^{\alpha}\right)\stackrel{4}{\Theta}_{ij} + \stackrel{4}{\Theta}_{\alpha\beta}F_{i}^{\alpha}F_{j}^{\beta} \right), \\ & \stackrel{6}{\Theta}_{ijk}^{h} \equiv \frac{1}{2} \left(F_{i}^{h}\mu_{(jk)} + F_{j}^{h}\mu_{[ik]} + F_{k}^{h}\mu_{[ij]} - \delta_{i}^{h}m_{(jk)} - \delta_{j}^{h}m_{[ik]} - \delta_{k}^{h}m_{[ij]} + \stackrel{1}{\Theta}_{ikj}^{h} \right), \\ & \stackrel{7}{\Theta}_{ijk} \equiv \mu_{\alpha}R_{kji}^{\alpha} + \frac{1}{2} \left(\stackrel{5}{\Theta}_{ij,k} + \stackrel{5}{\Theta}_{ik,j} - \stackrel{5}{\Theta}_{jk,i} \right), \qquad m_{ij} \equiv F_{i}^{\alpha}\mu_{\alpha j}, \end{split}$$

where $R_{ijk}^{h}(x)$ is the Riemann tensor of the space A_n . We denote by the brackets [i, k] an operation called antisymmetrization (or, alternation) without division with respect to the indices i and k.

Obviously, right hand sides of the equations (5) depend on unknown functions $F_i^h(x)$, $F_{ij}^h(x)$, $\mu_i(x)$, $\mu_{ij}(x)$, and on the components $\Gamma_{ij}^h(x)$ of the space A_n .

The equations (5) and (6) form a closed mixed system of PDE's of Cauchy type with respect to functions $F_i^h(x)$, $F_{ij}^h(x)$, $\mu_i(x)$, $\mu_{ij}(x)$. Also the mapping $\pi_2(e)$ depends on unknown functions $\psi_i(x)$, $\varphi_j(x)$ (see equations (2)).

An almost geodesic mapping π_2 for which $\psi_i \equiv 0$ is called *canonical*. It's known [28] that any almost geodesic mapping π_2 can be written as the composition of a canonical almost geodesic mapping of type π_2 and a geodesic mapping. The latter may be referred to as a trivial almost geodesic mapping.

Hence a canonical almost geodesic mapping $\pi_2(e)$ $(e = \pm 1)$, determined by the equations

$$P_{ij}^h = F_{(i}^h \varphi_{j)},\tag{7}$$

and also by the equations (5) and (6).

3 Canonical almost geodesic mappings $\pi_2(e)$ $(e = \pm 1)$ of spaces A_n with affine connection onto two-symmetric spaces

A space \overline{A}_n with affine connection is called two-symmetric if its Riemann tensor satisfies the condition

$$\overline{R}^{h}_{ijk|ml} = 0,$$

where \overline{R}_{ijk}^h is the Riemann tensor of the space \overline{A}_n . By the symbol "|" we denote a covariant derivative with respect to the connection of the space \overline{A}_n .

It is understood that in two-symmetric spaces \overline{A}_n the conditions

$$\overline{R}^h_{ijk|m} \neq 0$$

are satisfied.

Then the two-symmetric spaces are other than symmetric spaces.

We recall that symmetric spaces \overline{A}_n are characterized by

$$\overline{R}^h_{ijk|m} = 0.$$

Symmetric spaces were introduced by P.A. Shirokov [25] and É. Cartan [13], see also S. Helgason [14]. Geodesic mappings of this spaces were studied by N. S. Sinyukov [27], and I. Hinterleitner and J. Mikeš [15]. Geodesic mappings and holomorphically projective mappings of two-symmetric Riemannian spaces were stadied by J. Mikeš [18, 17], see [19, 20, 23, 27].

Let us consider the canonical almost geodesic mappings of type $\pi_2(e)$ $(e = \pm 1)$ of spaces A_n with affine connection onto two-symmetric spaces \overline{A}_n , which are determined by the equations (5), (6) and (7). Suppose, that the spaces are referred to the common coordinate system x^1, x^2, \ldots, x^n .

Since

$$\overline{R}^{h}_{ijk|m} = \frac{\partial \overline{R}^{h}_{ijk}}{\partial x^{m}} + \overline{\Gamma}^{h}_{m\alpha} \overline{R}^{\alpha}_{ijk} - \overline{\Gamma}^{\alpha}_{mi} \overline{R}^{h}_{\alpha jk} - \overline{\Gamma}^{\alpha}_{mj} \overline{R}^{h}_{i\alpha k} - \overline{\Gamma}^{\alpha}_{mk} \overline{R}^{h}_{ij\alpha},$$

then taking account of (1) we can obtain

$$\overline{R}^{h}_{ijk|m} = \overline{R}^{h}_{ijk,m} + P^{h}_{m\alpha}\overline{R}^{\alpha}_{ijk} - P^{\alpha}_{mi}\overline{R}^{h}_{\alpha jk} - P^{\alpha}_{mj}\overline{R}^{h}_{i\alpha k} - P^{\alpha}_{mk}\overline{R}^{h}_{ij\alpha}.$$
(8)

Since according to the definition of covariant derivative

$$\left(\overline{R}^{h}_{ijk|m}\right)_{,l} = \frac{\partial \overline{R}^{h}_{ijk|m}}{\partial x^{l}} + \Gamma^{h}_{\alpha l} \overline{R}^{\alpha}_{ijk|m} - \Gamma^{\alpha}_{il} \overline{R}^{h}_{\alpha jk|m} - \Gamma^{\alpha}_{jl} \overline{R}^{h}_{i\alpha k|m} - \Gamma^{\alpha}_{kl} \overline{R}^{h}_{ij\alpha|m} - \Gamma^{\alpha}_{ml} \overline{R}^{h}_{ijk|\alpha},$$

then taking account of (1), we have

$$(\overline{R}^{h}_{ijk|m})_{,l} = \overline{R}^{h}_{ijk|ml} - P^{h}_{\alpha l} \overline{R}^{\alpha}_{ijk|m} + P^{\alpha}_{il} \overline{R}^{h}_{\alpha jk|m} + P^{\alpha}_{jl} \overline{R}^{h}_{i\alpha k|m} + P^{\alpha}_{kl} \overline{R}^{h}_{ij\alpha|m} + P^{\alpha}_{ml} \overline{R}^{h}_{ijk|\alpha}.$$

$$(9)$$

Differentiating (8) with respect to x^l in the space A_n , we obtain

$$\left(\overline{R}_{ijk|m}^{h}\right)_{,l} = \overline{R}_{ijk,ml}^{h} + P_{m\alpha,l}^{h} \overline{R}_{ijk}^{\alpha} + P_{m\alpha}^{h} \overline{R}_{ijk,l}^{\alpha} - P_{mi,l}^{\alpha} \overline{R}_{\alpha jk}^{h} - P_{mi}^{\alpha} \overline{R}_{\alpha jk,l}^{h} - P_{mj,l}^{\alpha} \overline{R}_{i\alpha k}^{h} - P_{mj}^{\alpha} \overline{R}_{i\alpha k,l}^{h} - P_{mk,l}^{\alpha} \overline{R}_{ij\alpha}^{h} - P_{mk}^{\alpha} \overline{R}_{ij\alpha,l}^{h}.$$

$$(10)$$

Substituting in (9) from (10), we have

$$\overline{R}^{h}_{ijk,ml} = \overline{R}^{h}_{ijk|ml} - P^{h}_{\alpha l} \overline{R}^{\alpha}_{ijk|m} + P^{\alpha}_{il} \overline{R}^{h}_{\alpha jk|m} + P^{\alpha}_{jl} \overline{R}^{h}_{i\alpha k|m} + P^{\alpha}_{kl} \overline{R}^{h}_{ij\alpha|m}
+ P^{\alpha}_{ml} \overline{R}^{h}_{ijk|\alpha} - P^{h}_{m\alpha,l} \overline{R}^{\alpha}_{ijk} - P^{h}_{m\alpha} \overline{R}^{\alpha}_{ijk,l} + P^{\alpha}_{mi,l} \overline{R}^{h}_{\alpha jk} + P^{\alpha}_{mi} \overline{R}^{h}_{\alpha jk,l}
+ P^{\alpha}_{mj,l} \overline{R}^{h}_{i\alpha k} + P^{\alpha}_{mj} \overline{R}^{h}_{i\alpha k,l} + P^{\alpha}_{mk,l} \overline{R}^{h}_{ij\alpha} + P^{\alpha}_{mk} \overline{R}^{h}_{ij\alpha,l}.$$
(11)

Suppose that the space \overline{A}_n is a two-symmetric space. Then the formula (7) holds. Hence from (11) we obtain

$$\overline{R}^{h}_{ijk,ml} = -P^{h}_{\alpha l}\overline{R}^{\alpha}_{ijk|m} + P^{\alpha}_{il}\overline{R}^{h}_{\alpha jk|m} + P^{\alpha}_{jl}\overline{R}^{h}_{i\alpha k|m} + P^{\alpha}_{kl}\overline{R}^{h}_{ij\alpha|m}
+ P^{\alpha}_{ml}\overline{R}^{h}_{ijk|\alpha} - P^{h}_{m\alpha,l}\overline{R}^{\alpha}_{ijk} - P^{h}_{m\alpha}\overline{R}^{\alpha}_{ijk,l} + P^{\alpha}_{mi,l}\overline{R}^{h}_{\alpha jk} + P^{\alpha}_{mi}\overline{R}^{h}_{\alpha jk,l}
+ P^{\alpha}_{mj,l}\overline{R}^{h}_{i\alpha k} + P^{\alpha}_{mj}\overline{R}^{h}_{i\alpha k,l} + P^{\alpha}_{mk,l}\overline{R}^{h}_{ij\alpha} + P^{\alpha}_{mk}\overline{R}^{h}_{ij\alpha,l}.$$
(12)

We introduce the tensor \overline{R}_{ijkm}^h defined by

$$\overline{R}^{h}_{ijk,m} = \overline{R}^{h}_{ijkm}.$$
(13)

It's known [27, 28] that the Riemann tensors of the spaces A_n and \overline{A}_n are related to each other by the equations

$$\overline{R}_{ijk}^{h} = R_{ijk}^{h} + P_{ik,j}^{h} - P_{ij,k}^{h} + P_{ik}^{\alpha} P_{\alpha j}^{h} - P_{ij}^{\alpha} P_{\alpha k}^{h}.$$
(14)

Since the deformation tensor of the mapping $P_{ij}^h(x)$ is represented by the equations (6), it follows from (14) that

$$\varphi_{i,j}F_k^h + \varphi_{k,j}F_i^h - \varphi_{i,k}F_j^h - \varphi_{j,k}F_i^h = C_{ijk}^h, \tag{15}$$

where

$$C_{ijk}^{h} = \overline{R}_{ijk}^{h} - R_{ijk}^{h} - \varphi_{i} \left(F_{kj}^{h} + \varphi_{\alpha} F_{k}^{\alpha} F_{j}^{h} + e \delta_{k}^{h} \varphi_{j} - F_{jk}^{h} - \varphi_{\alpha} F_{j}^{\alpha} F_{k}^{h} - e \delta_{j}^{h} \varphi_{k} \right) + \varphi_{k} \left(F_{ij}^{h} + \varphi_{\alpha} F_{i}^{\alpha} F_{j}^{h} \right) - \varphi_{j} \left(F_{ik}^{h} + \varphi_{\alpha} F_{i}^{\alpha} F_{k}^{h} \right).$$

Let us multiply (15) by F_l^m and contract for l and h. Hence we have

$$\delta_k^m \varphi_{i,j} + \delta_i^m \varphi_{k,j} - \delta_j^m \varphi_{i,k} - \delta_i^m \varphi_{j,k} = e C_{ijk}^\alpha F_\alpha^m.$$
(16)

Contracting the equations (16) for m and i we get

$$\varphi_{k,j} - \varphi_{j,k} = \frac{e}{n+1} C^{\alpha}_{\beta jk} F^{\beta}_{\alpha}.$$
(17)

Again, contracting the equations (16) for m and k we get

$$n\varphi_{i,j} - \varphi_{j,i} = eC^{\alpha}_{ij\beta}F^{\beta}_{\alpha}.$$
(18)

Taking account of (17) the equations (18) can be written as

$$\varphi_{i,j} = \frac{e}{n-1} \left(C^{\alpha}_{ij\beta} - \frac{1}{n+1} C^{\alpha}_{\beta ji} \right) F^{\beta}_{\alpha}.$$
(19)

And finally, taking account of (4), (6) and (13) the equations (12) can be written as

$$\overline{R}^{h}_{ijkm,l} = -F^{h}_{(\alpha}\varphi_{l)}\overline{R}^{\alpha}_{ijk|m} + F^{\alpha}_{(i}\varphi_{l)}\overline{R}^{h}_{\alpha jk|m} + F^{\alpha}_{(j}\varphi_{l)}\overline{R}^{h}_{i\alpha k|m} + F^{\alpha}_{(k}\varphi_{l)}\overline{R}^{h}_{ij\alpha|m}
+ F^{\alpha}_{(m}\varphi_{l)}\overline{R}^{h}_{ijk|\alpha} - \left(F^{h}_{(m|l|}\varphi_{\alpha)} + F^{h}_{(m}\varphi_{\alpha),l}\right)\overline{R}^{\alpha}_{ijk} - F^{h}_{(m}\varphi_{\alpha)}\overline{R}^{\alpha}_{ijkl}
+ \left(F^{\alpha}_{(m|l|}\varphi_{i)} + F^{\alpha}_{(m}\varphi_{i),l}\right)\overline{R}^{h}_{\alpha jk} + F^{\alpha}_{(m}\varphi_{i)}\overline{R}^{h}_{\alpha jkl} + \left(F^{\alpha}_{(m|l|}\varphi_{j)} + F^{\alpha}_{(m}\varphi_{j),l}\right)\overline{R}^{h}_{i\alpha k}
+ F^{\alpha}_{(m}\varphi_{j)}\overline{R}^{h}_{i\alpha kl} + \left(F^{\alpha}_{(m|l|}\varphi_{k)} + F^{\alpha}_{(m}\varphi_{k),l}\right)\overline{R}^{h}_{ij\alpha} + F^{\alpha}_{(m}\varphi_{k)}\overline{R}^{h}_{ij\alphal}.$$
(20)

Suppose, that in the equations (20) the tensors $\overline{R}_{ijk|m}^{h}$ and $\varphi_{i,j}$ are expressed according to (8) and (19). Also we suppose that $\overline{R}_{ijk,m}^{h} = \overline{R}_{ijkm}^{h}$. Obviously, in the space A_n the equations (4), (13), (19) and (20) form a closed mixed system of PDE's of Cauchy type with respect to functions $F_i^h(x)$, $F_{ij}^h(x)$, $\mu_i(x)$, $\mu_{ij}(x)$, $\overline{R}_{ijk}^h(x)$, $\overline{R}_{ijkm}^h(x)$, $\varphi_i(x)$, and the functions $F_i^h(x)$, $F_{ij}^h(x)$, $\mu_{ij}(x)$ are algebraic conditions (5). The algebraic conditions for the functions $\overline{R}_{ijk}^h(x)$ and $\overline{R}_{ijkm}^h(x)$ are

$$\overline{R}_{i(jk)}^{h} = 0, \quad \overline{R}_{(ijk)}^{h} = 0, \quad \overline{R}_{i(jk)m}^{h} = 0, \quad \overline{R}_{(ijk)m}^{h} = 0, \\
\overline{R}_{i(jkm)}^{h} = -F_{(m}^{h}\varphi_{\alpha})\overline{R}_{ijk}^{\alpha} - F_{(k}^{h}\varphi_{\alpha})\overline{R}_{imj}^{\alpha} - F_{(j}^{h}\varphi_{\alpha})\overline{R}_{ikm}^{\alpha} \\
+ F_{(m}^{\alpha}\varphi_{i)}\overline{R}_{\alpha jk}^{h} + F_{(k}^{\alpha}\varphi_{i)}\overline{R}_{\alpha mj}^{h} + F_{(j}^{\alpha}\varphi_{i)}\overline{R}_{\alpha km}^{h}.$$
(21)

Hense we have proved

Theorem. In order that a space A_n with affine connection admits an almost geodesic mappings of type $\pi_2(e)$ $(e = \pm 1)$ onto a two-symmetric space \overline{A}_n , it is necessary and sufficient that the

mixed system of differential equations of Cauchy type in covariant derivatives (5), (6), (13), (19), (20), (21) has a solution with respect to functions $F_i^h(x)$, $F_{ij}^h(x)$, $\mu_i(x)$, $\mu_{ij}(x)$, $\overline{R}_{ijk}^h(x)$, $\overline{R}_{ijkm}^h(x)$, $\varphi_i(x)$.

It's obvious, that the general solution of the mixed system of Cauchy type depends on no more then $\frac{1}{2}n(n^4-1)$ essential parameters.

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